

Water Level Monitoring Method of Channel Water Gauge Image Based on Unet and ResNet50

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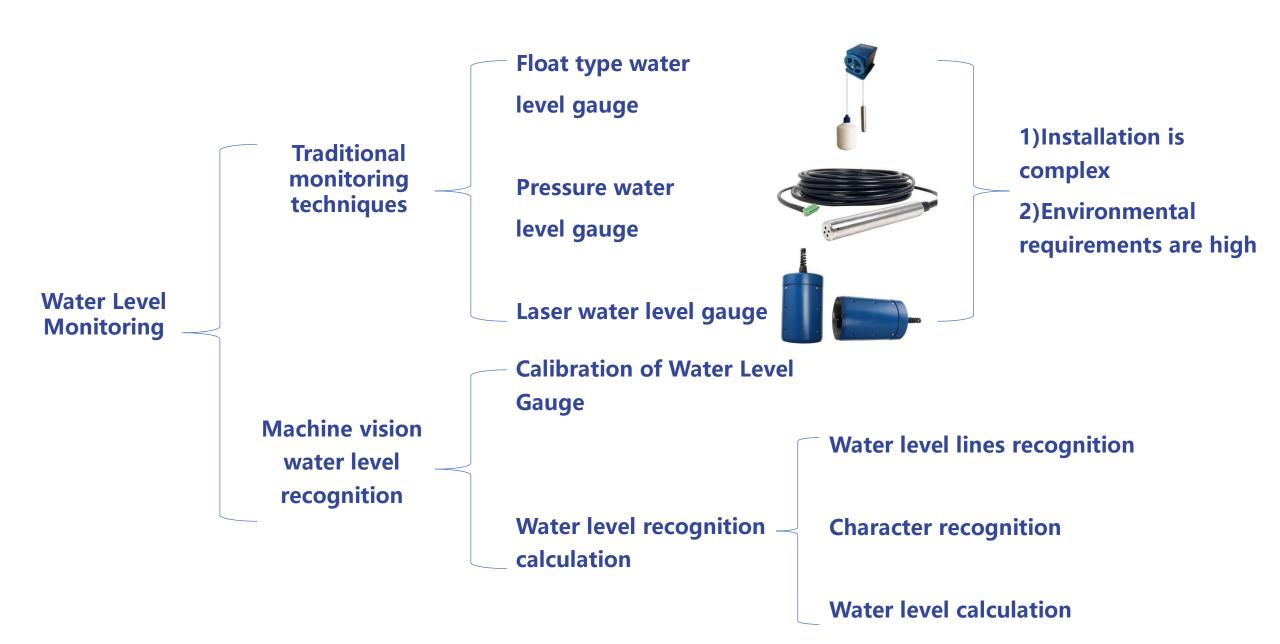


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Content

- Introduction
- Basic Principles
- Experimental test results and analysis



1.Calibration of Water Level Gauge

1)Image Processing

a.Set edge connectivity threshold to select water level gauge -Sun et al

DA: Not suitable for complex environments, relies on accuracy of

edge detection, lacks universality.

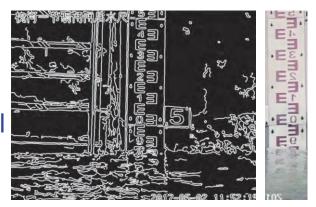
2)Manual Calibration

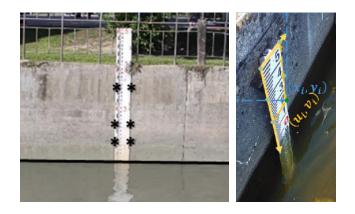
- a.Determine initial orientation of camera on-site -Lin et al
- b.Determine initial orientation of gauge on-site -Zhang et al
- **DA:** Requires human participation, significant recognition errors can

occur when the camera position changes.

3)Deep Learning

a.YOLOv5s Model - Qiao et al







2. <u>Water level recognition calculation</u>:

combined with water level lines, character recognition, unit pixel actual length calculation

1)Identification of water level lines

a.Marginal features - Sun et al., Lin et al., 2018

DA: Errors are easier to identify in more complex environments

b.Projection method-Lin et al., 2013, Li et al., Qiao et al

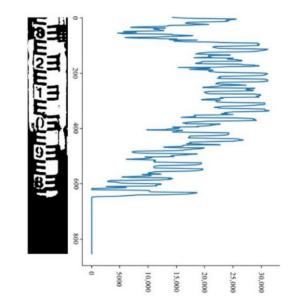
DA: Errors are easier to identify in more complex environments

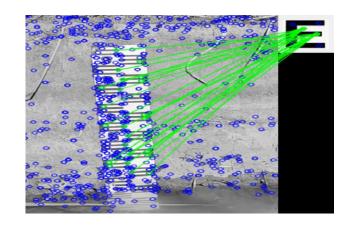
2)Recognition of characters

a.Template matching algorithm - Lin et al., 2013 DA: Poor accuracy and adaptability

b.Neural network algorithms

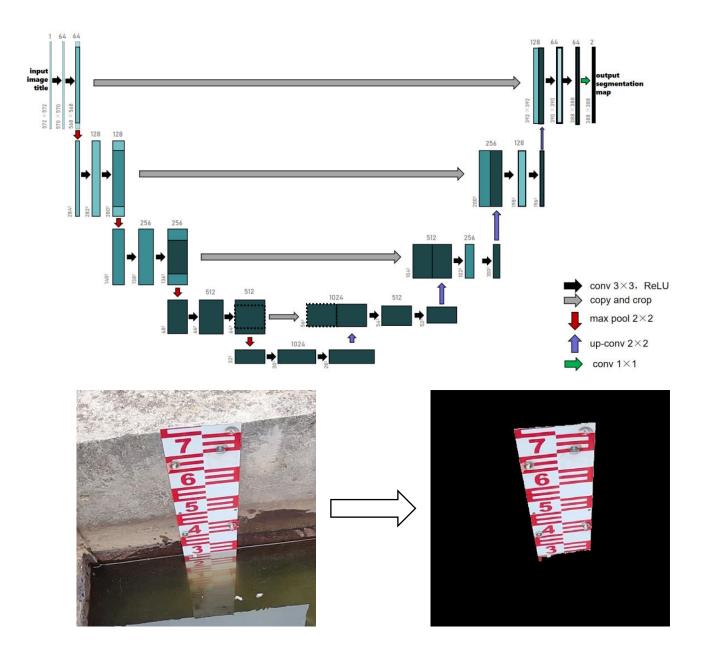
DA: Heavy workload





Advantages:

- 1) Reduced model complexity
- 2) Better preserved image features
- 3) Able to handle complex environment scale images well
- 4) No longer requires the recognition of edge and water level lines compared to YOLO.



1.Canny Operator Pros:

- 1)Refine the edges of an image,
- 2)Automatically connect discontinuities
- 3)Enhance the edge detection's noise resistance ability, and accurately detect edges.

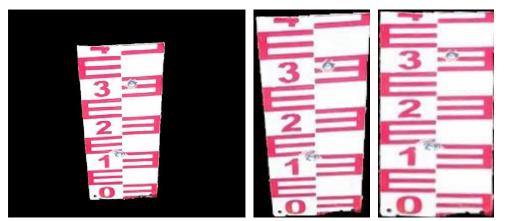
2.Geometrically Correct Steps

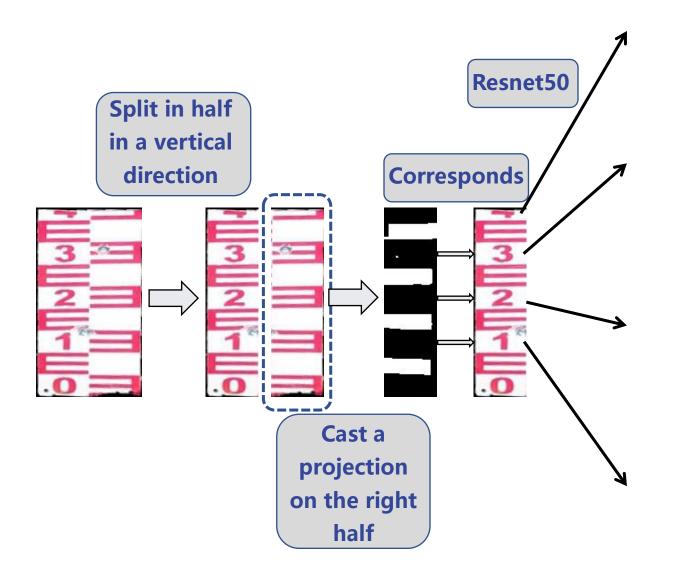
Determine the pre-correction draft vertex coordinates
Generate a perspective transformation matrix
Geometrically correct

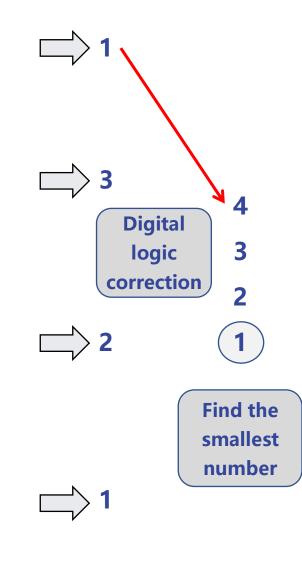
The formula for perspective transformation is:

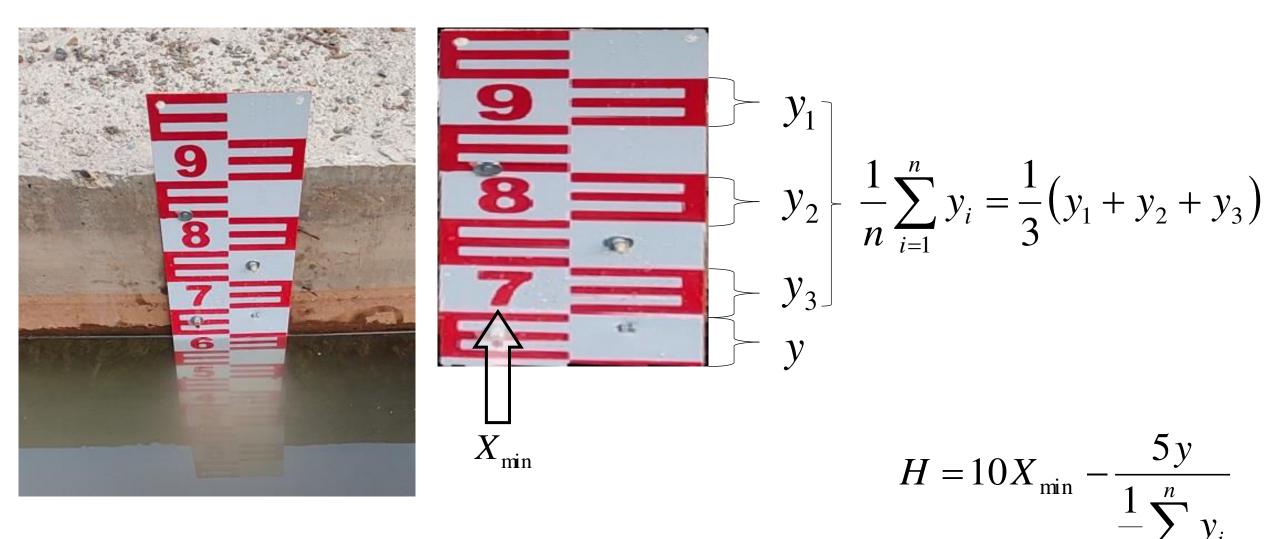
$$[x', y', 1] = [u, v, 1] \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$



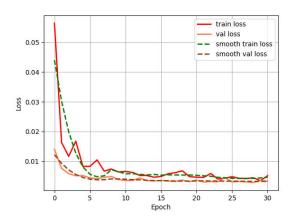


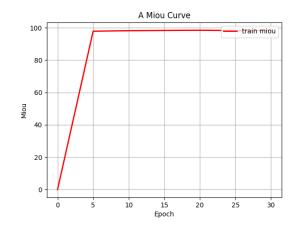


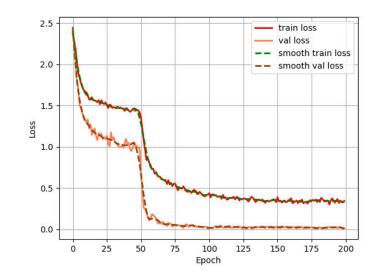


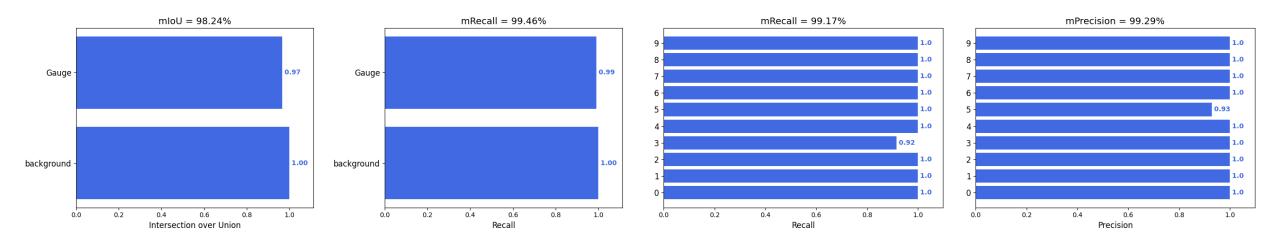


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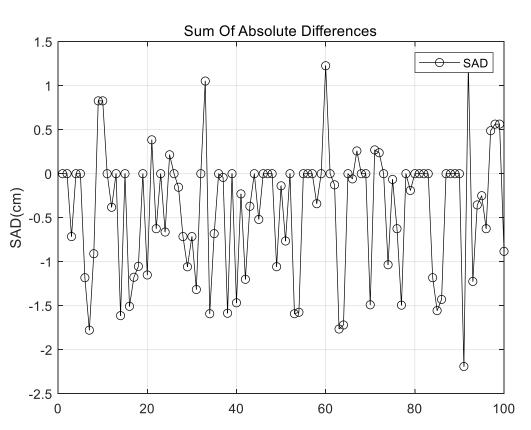


	mIoU	mPrecison	mRecall	Accuracy	top-1 Accuracy
VGG16	98.24	98.76	99.46	99.84	١
ResNet50	١	99.29	99.17	١	99.59

The test results show :

The water level reading error is basically below 2cm,

The average absolute error is about 0.5595cm





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